Computational Complexity III: Limits of Computation

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Context

- Section 1: Computational Complexity
- Section 2: Polynomial time reduction
- 3 Section 3: Space Complexity

Computability vs Complexity

Computability

What can be computed and what can not be computed?

Complexity

What can be computed fast and what can not be computed?

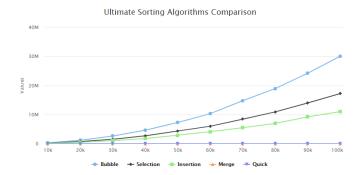
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Complexity

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Time Complexity of DTM

Definition

Let $t: \mathbb{N} \longrightarrow \mathbb{N}$ increasing function. The **time complexity** of DTIME[t(n)] is the collection of all languages that are decidable by an O(t(n)) time DTM.

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DTIME[t(n)] \equiv \{ P: P \text{ is solved in } O(t(n)) \text{ time } \}
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Definition

Complexity class \mathcal{P} is the set of decision problems that can be solved by a DTM in a polynomial time of steps.

$$\mathcal{P} \equiv \bigcup_{k \geq 0} DTIME[n^k]$$

Cook - Karp Thesis

The **Cook** - **Karp Thesis** states that decision problems that are "tractably computable" can be computed by a DTM in polynomial time, i.e., are in \mathcal{P} .





Time Complexity of NTM

Definition

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 $NTIME[t(n)] \equiv \{ P: P \text{ is solved in non deterministic time } O(t(n)) \}$

Time Complexity of NTM

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 $\mathsf{NTIME}[\mathsf{t}(\mathsf{n})] \equiv \{ \ \mathsf{P} : \mathsf{P} \ \mathsf{is} \ \mathsf{solved} \ \mathsf{in} \ \mathsf{non} \ \mathsf{deterministic} \ \mathsf{time} \ \mathsf{O}(\mathsf{t}(\mathsf{n})) \ \}$

Definition

Complexity class \mathcal{NP} is the set of decision problems that can be solved by a NTM in a polynomial time of steps or is the set of decision problems for which there exists a **poly time certifier**.

$$\mathcal{NP} \equiv \bigcup_{k>0} NTIME[n^k]$$

How much easier is to **find** a solution than to **confirm** it?

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$$\mathcal{P} \subseteq \mathcal{NP}$$

Open Problem: $\mathcal{P} \supseteq^{???} \mathcal{NP}$





$\mathsf{TSP} \in \mathcal{NP}$

Travelling Salesman Problem (TSP): Given a set of distances on n cities and a bound D, is there a tour of length at most D?

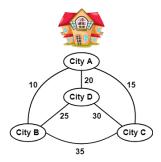


Figure: TSP

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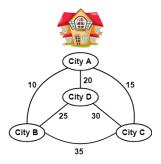


Figure: TSP

Certificate: A tour of given graph.

Certifier:

- 1. Check that each city appears once.
- 2. Check that the length of tour is at most D.

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Figure: The casting process



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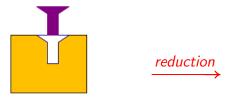


Figure: The casting process



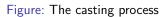






Figure: Half plane intersection

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Definition

 $X \in \mathcal{NP}$ -complete if:

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Hamiltonian Cycle Problem

reduction Travelling Salesman Problem

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Let G = (V, E) a graph. Find whether G contains a cycle that passes through all vertices of the graph exactly once.

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Find whether *G* contains a cycle that passes through all vertices of the graph exactly once.





Travelling Salesman Problem

Let $G^{'} = (V^{'}, E^{'})$ a weighted graph with non negative weights and $k^{'} \in \mathbb{Z}$.

Find whether $G^{'}$ contains a cycle that passes through all vertices of the graph exactly once and has length $\leq k^{'}$.

Goal of the study of \mathcal{NP} - completeness

If some \mathcal{NP} - complete problem P is in \mathcal{P} , then $\mathcal{P}=\mathcal{NP}$.

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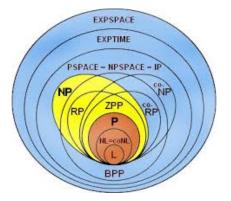


Figure: Scott Aaronson

Context

- Section 1: Computational Complexity
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Definition

Let s: $\mathbb{N} \longrightarrow \mathbb{N}$ increasing function. The **space complexity** of DSPACE[t(n)] is the collection of all languages that are decidable by an O(s(n)) space DTM.

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NSPACE[s(n)] \equiv \{ P: P \text{ is solved in } O(s(n)) \text{ space} \}
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Definition

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Definition

Complexity class PSPACE is the set of decision problems that can be solved by a (multitape) DTM in a polynomial number of SPACEs on the tape.

 $PSPACE \equiv \bigcup_{k>0} DSPACE[n^k]$

Theorem

 $\mathcal{P} \subseteq PSPACE$

Theorem

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Open Problem: $\mathcal{P} \supseteq^{???} \mathcal{NP} \supseteq^{???} \textit{PSPACE}$



PSPACE-complete

Definition

 $X \in PSPACE$ -complete if:

- X ∈ PSPACE
- $\forall Y \in PSPACE, Y \leq_P X$

GAMES

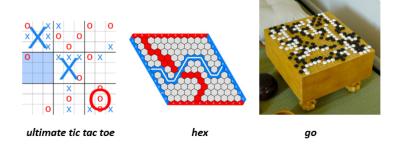


Figure: PSPACE-complete problems

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Thank you!